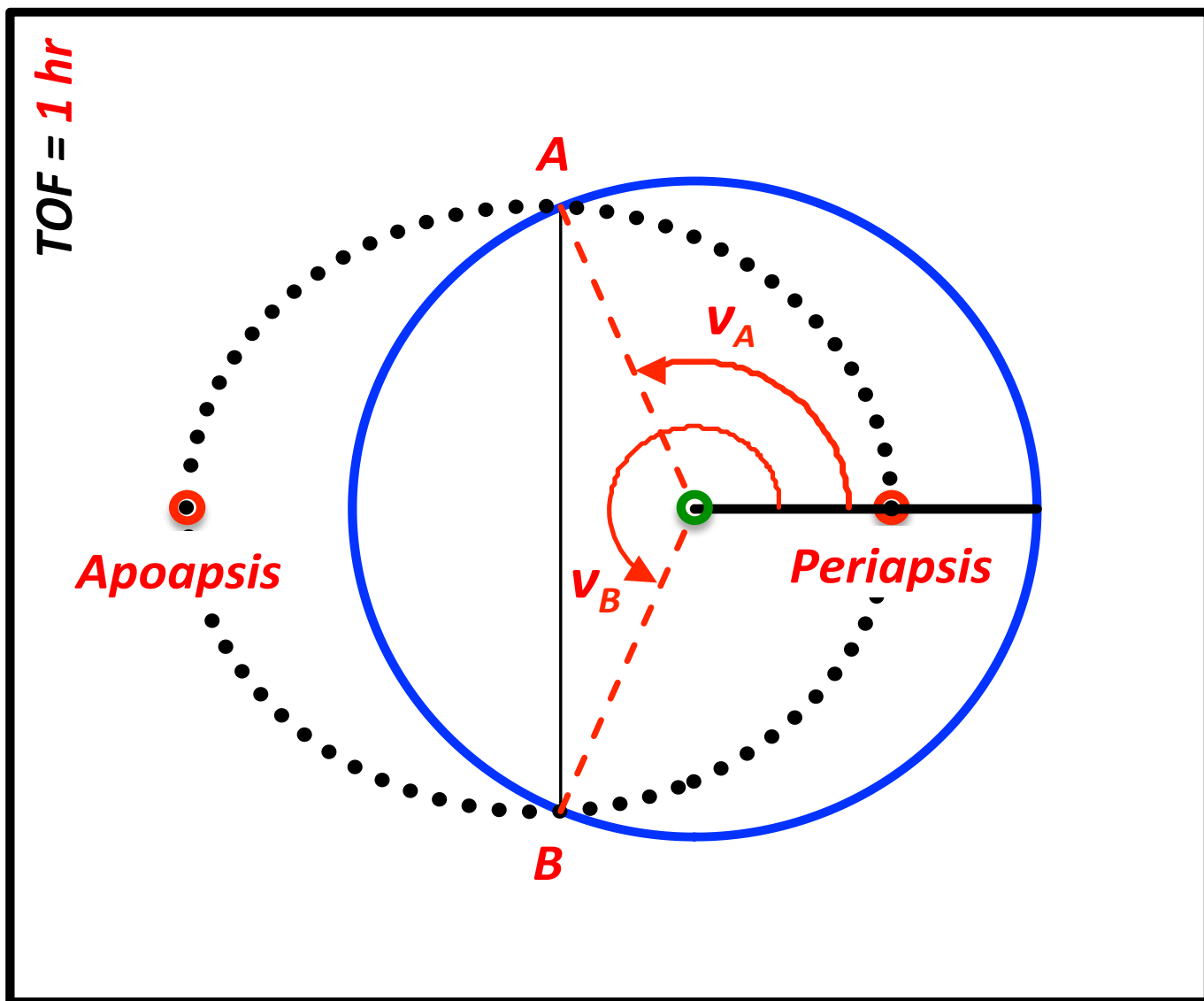


# SUBORBITAL ANALYSIS: THE A-to-B PROBLEM IN PLANETARY SCIENCE

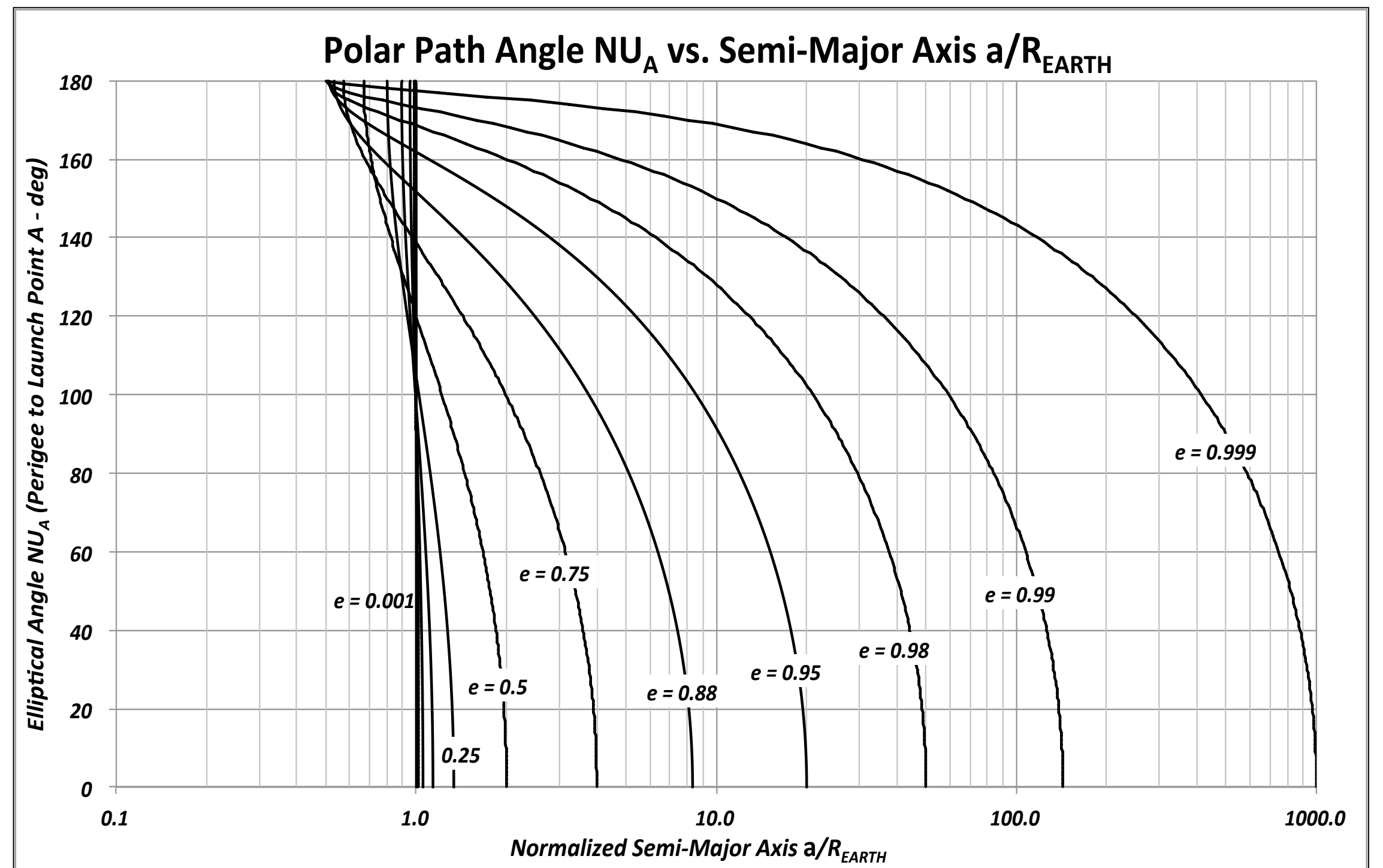
## TIME OF FLIGHT (TOF): CORRELATING EJECTA & STREWN TO SOURCE

Derivations Within This SUBORBITAL ANALYSIS Are Based On The Simplified Two-Body Model Where The Satellite Is Assumed To Be Massless. System Mass Is Concentrated At The Center Of The Central Body, Which Is Also The Coordinate Origin Of The Body-Centered Inertial Frame. Higher Order Terms Are Neglected, Such As Planetary Oblateness, Lunar Gravity, Solar Pressure, Electro-Magnetic & Atmospheric Effects.

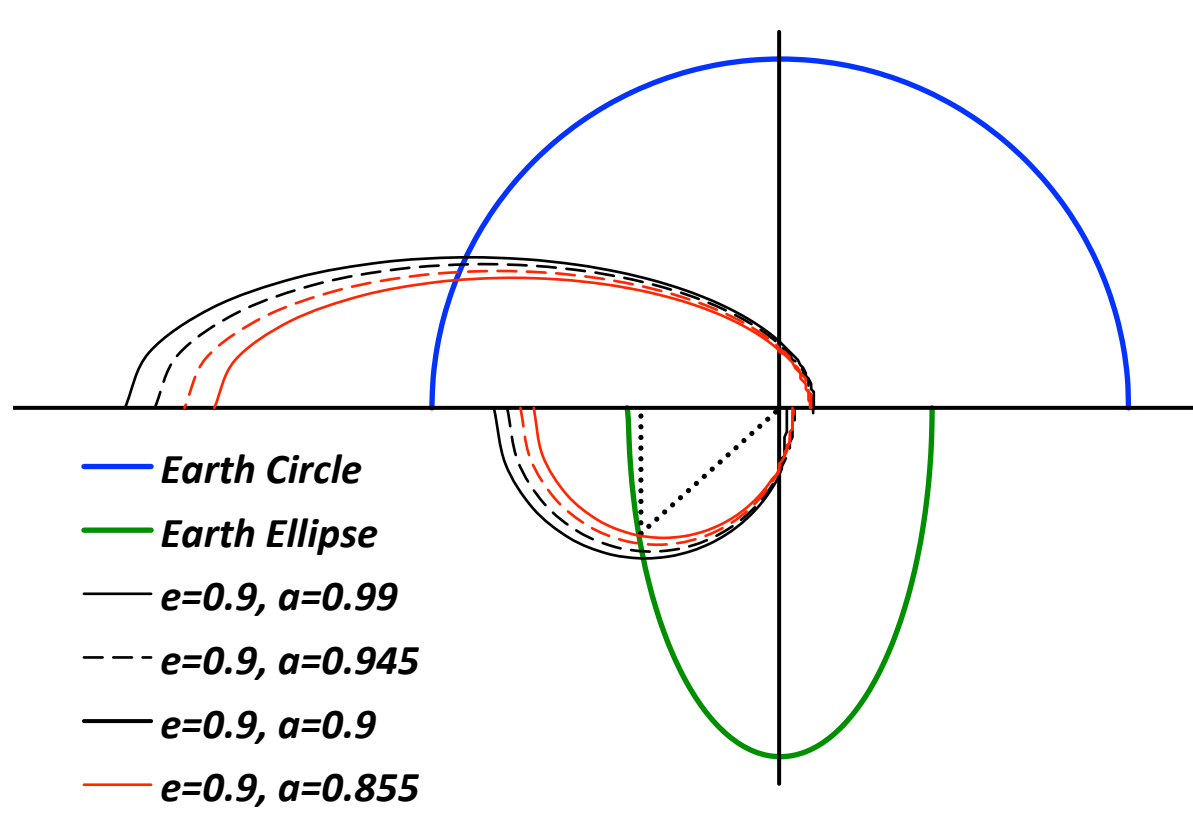
**Basic Suborbital Trajectory: A-to-B Chord & Central Angles (Scaled To Earth's Gravity)**



**Suborbital Time Of Flight (TOF) Depends On Eccentricity "e" AND Semi-Major Axis "a" Instead of Semi-Major Axis Only as in FULL Orbits (Kepler's 3<sup>rd</sup> Law).**

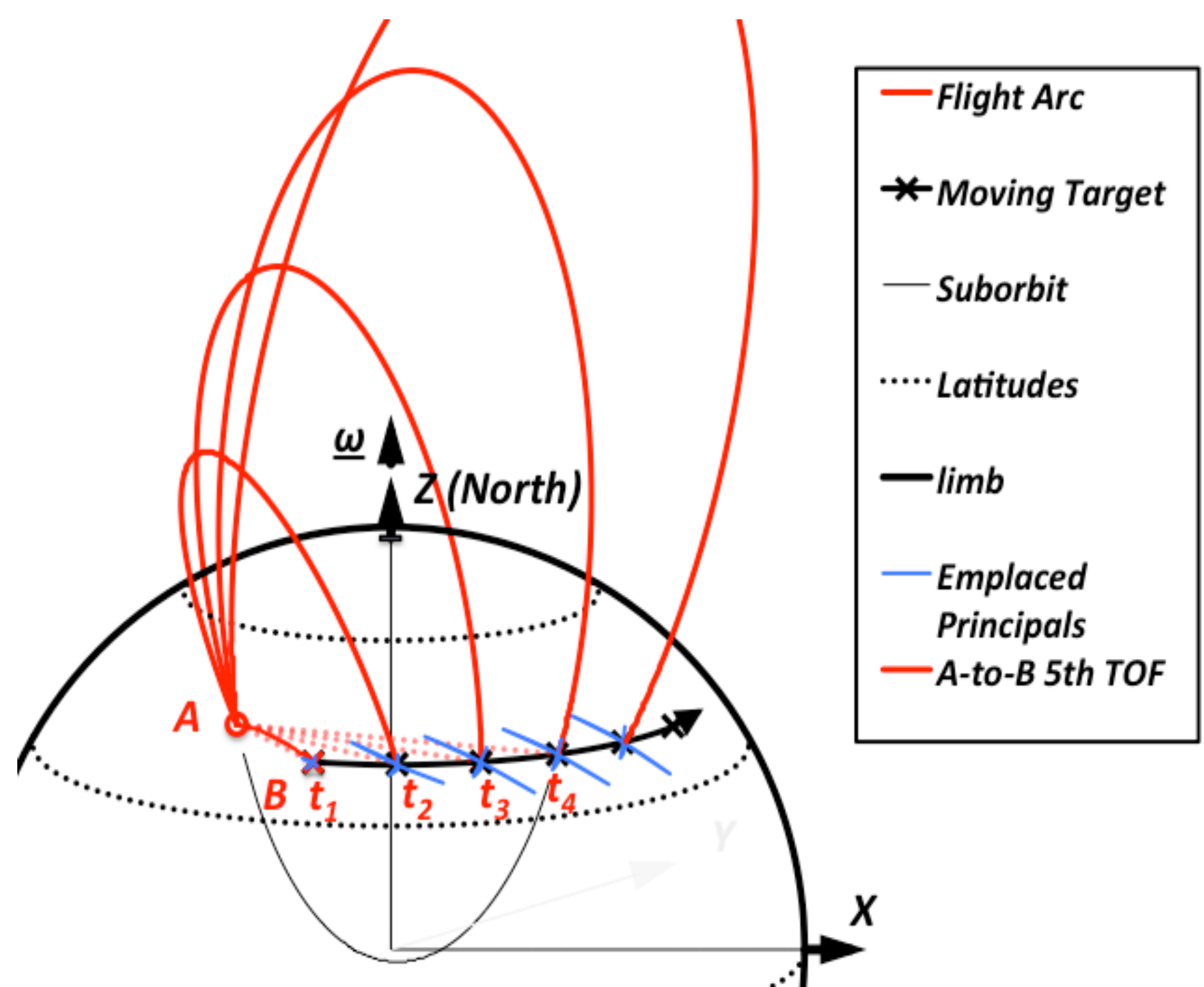


**Normal and Oblique Plane Views: The b-Circle For TOF Calculation Per Kepler's 2<sup>nd</sup> Law: Constant Area Sweep Rate**



**The Oblique Plane View Makes The Orbit Into A Circle Of Radius = "b": b Is The Semi-Minor Axis, So That Calculating Swept Area Is Trivial**

**Infinite Different A-to-B Trajectories Exist, Each With A Different TOF Value, For A Rotating Planet. This Complicates Analysis.**

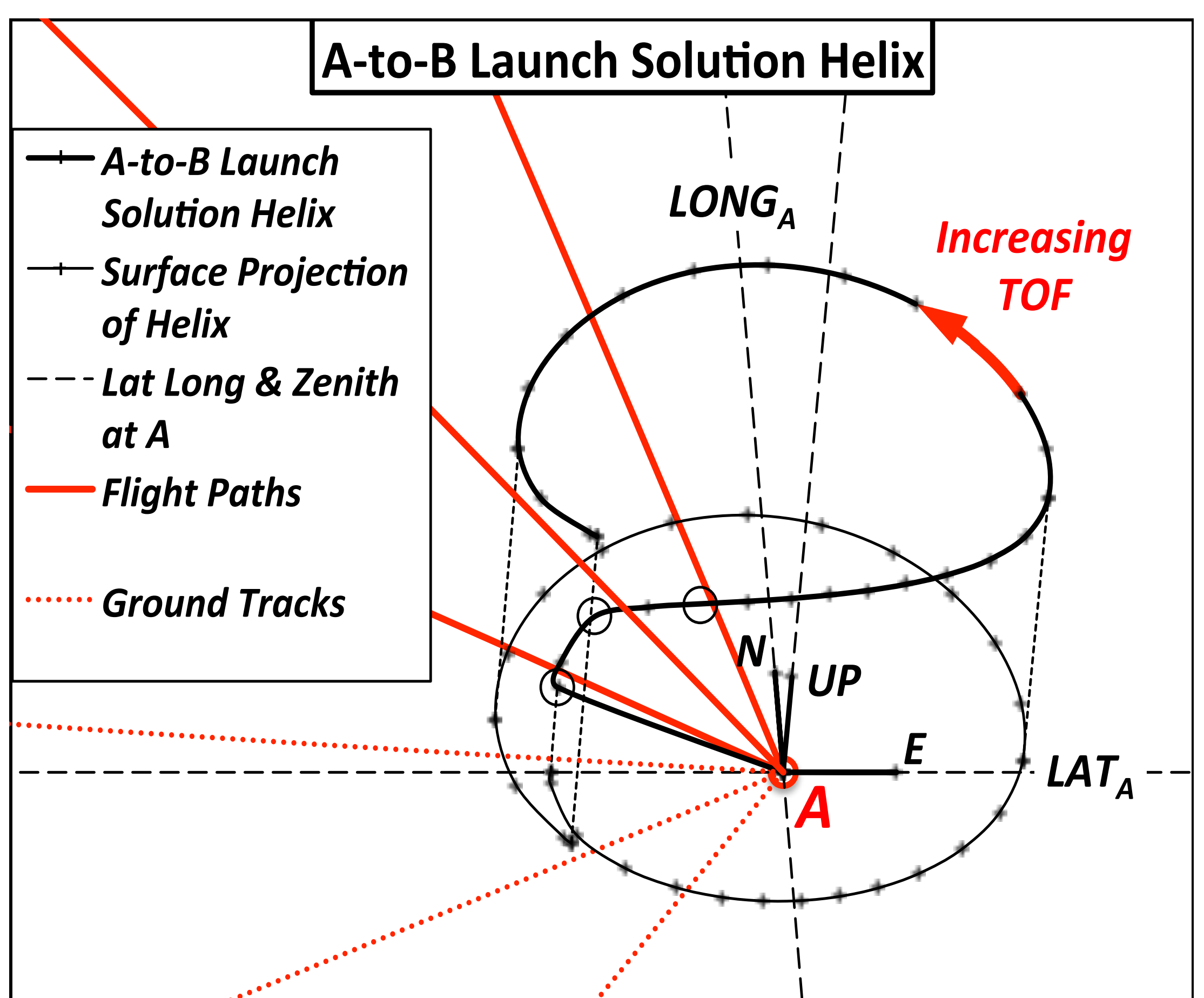
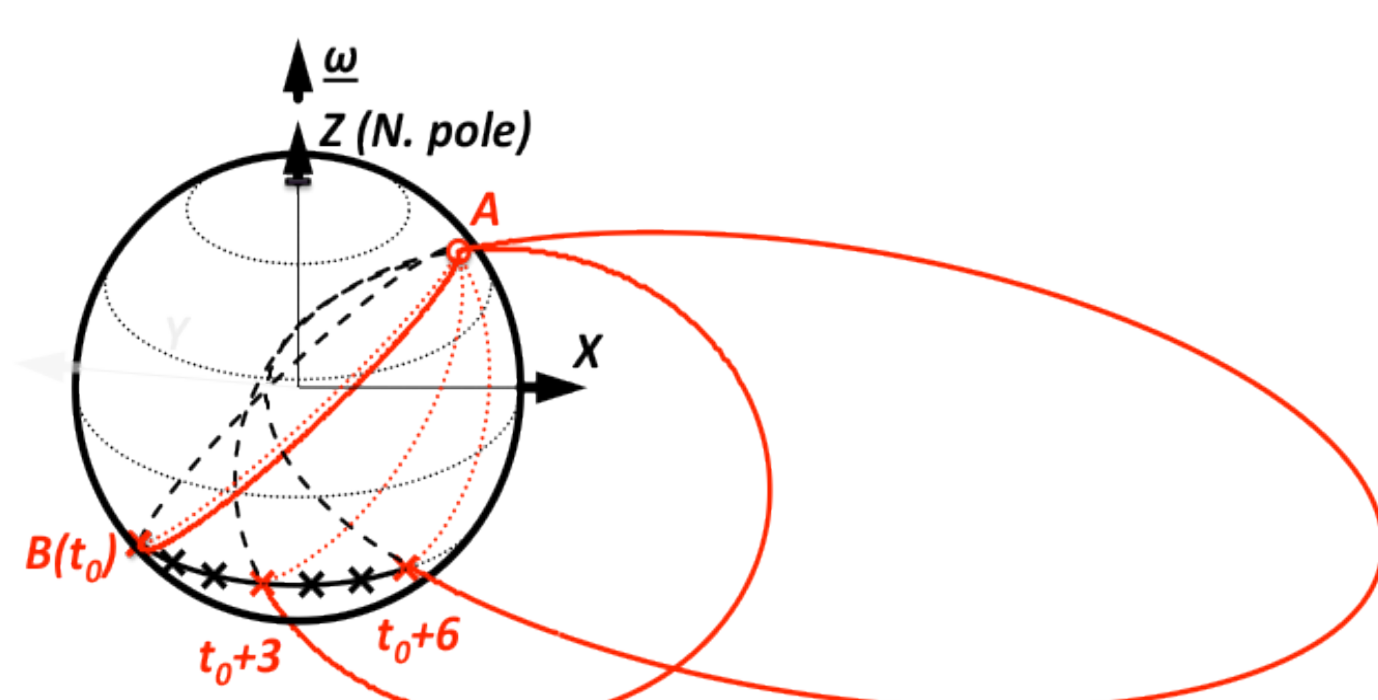
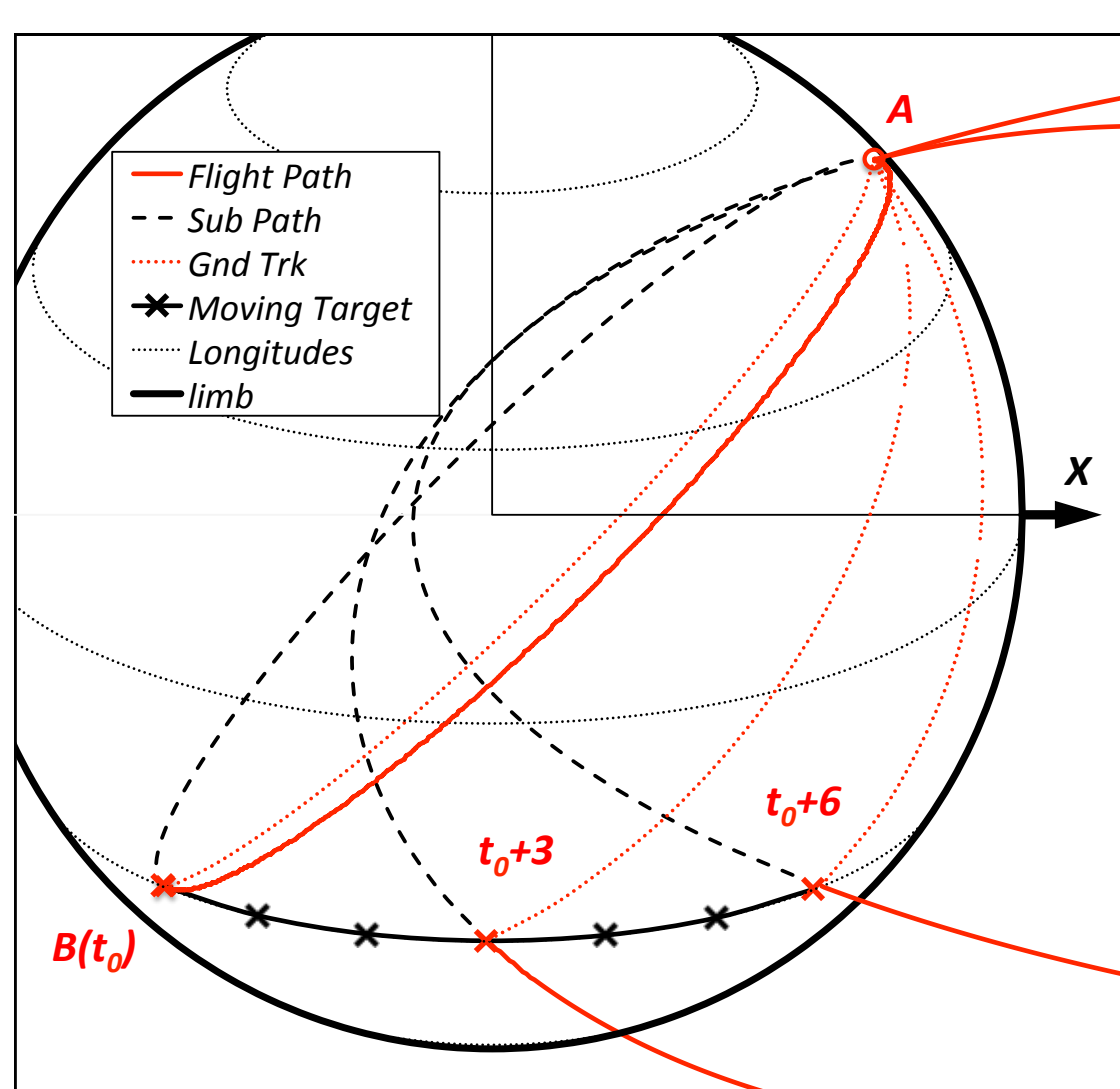
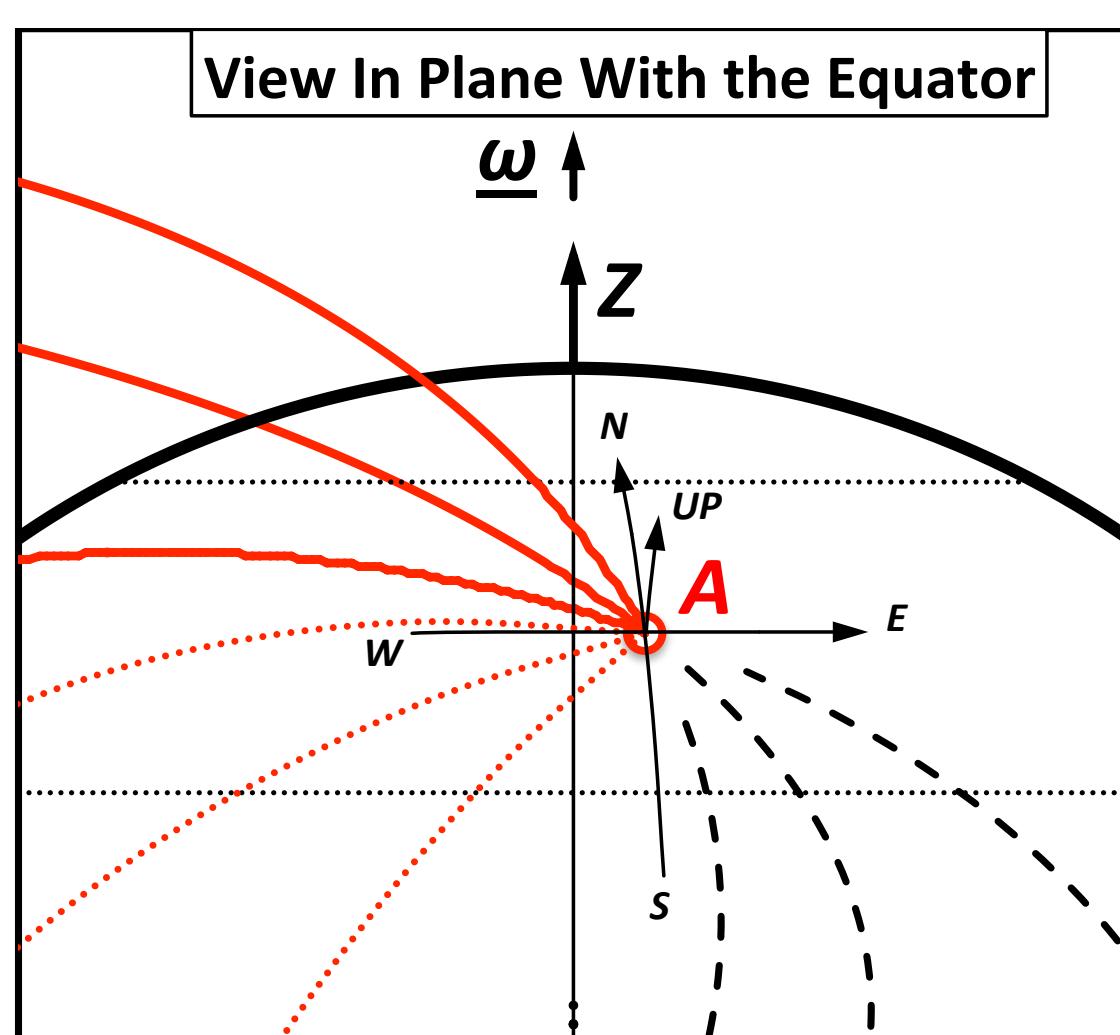


**Infinite Trajectories Exist To Get From A-to-B: One Solution For Each Discrete TOF While B Rotates Through Inertial Space.**

**The Set Of All Solution Trajectories For A Given A-To-B Pair May Be Defined By The A-To-B Launch Solution Helix. This Useful Format Always Has Common Features From Bottom Up:**

- ◆ A Base Leg Starting At The Min TOF Solution Trajectory
- ◆ A Minimum KE Point Just Above Min TOF Point
- ◆ A Transition Or "Knee" where  $\Delta EL$  Gives Way To  $\Delta AZ$
- ◆ An AZ Arc Which May Encircle 1, 2 or No Poles
- ◆ A "Day Later" Point On Approximately The Min TOF AZ

**The Min TOF Trajectory Is Defined By A Circular Orbit At Zero Altitude, Smooth Spherical Planet, No Atmosphere. The Launch Solution Helix Is Defined In The Local Topocentric (Earth-Fixed) Frame For Comparison To Lab Test Ejection Patterns.**



**The A-To-B Launch Solution Helix Is Defined By Kinetic Energy Launch Vectors in Azimuth (AZ), Elevation (EL), and Magnitude Normalized To Earth Escape KE Or EEKE.**