

The Easy way to Computational Geodynamics

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Companions in the new world of Big Data:

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Numerical Modeling and Big Data

- Numerical Modellers model the physics with forward simulations. Key issues:
 - Model sizes increase. 3D models can output billions of data points per timesteps. Timesteps can be thousands.
 - Performance. <u>The computing challenge</u>. Scalability is the key.
 - Parallel programming is important. Solving PDE's requires fastest bandwidth available.
 - Pedagogy. How and when should students and professional learn numerical modeling?

Numerical Modeling and Big Data

- Numerical Modellers simulate the physics with forward simulations. Present solutions:
 - Model size. Selecting and compressing the output. Dimension reduction. I will present one example. Future machine learning. Can we use entropy to measure how much to record?
 - Performance. Hierarchical methods, like multigrid and multipole. I will show one example. New algorithms also welcome. Big problem.
 - Parallel programming. MPI is the main tool. GPUs and MICs also used. Heterogeneous parallel computing is the future.
 - Pedagogy. Python and its libraries: Numpy, Matplotlib, Cython, mpi4py, ... <u>We don't need Matlab anymore. Python</u> is easier to learn and to use. New languages are emerging.

Geodynamic Motivation

Porous systems

Two phase flow





The computing challenge: particle in cell

- o Scalability
 - 1. Finite Differences and Finite Elements span maximum three orders of magnitude in space (10^9 cells = 1000^3).
 - 2. However particles allow increasing details. Particle advection can be immediately vectorized and do not weight on the overall computing time.
 - 3. Projection from and to lattice can be vectorized with a compact procedure.
- Implemented in Numerical Python. Easy to program.

The computing challenge: particle in cell

Implementation of the cell $\leftarrow \rightarrow$ particle projections using NumPy.

```
def projectLatticeToParticles (w1, w2, w3, w4, trIX, trIY, f, ft):
          ft[:]=(w1[:]*f[trIX[:],
                                                                                One line.
                     trIY[:]]+w2[:]*f[trIX[:]+1,
                                                                                Vectorized.
                     trIY[:]]+w3[:]*f[trIX[:],
                                                                                Extremely fast.
                     trIY[:]+1]+w4[:]*f[trIX[:]+1,
                     trIY[:]+1]) / (w1[:]+w2[:]+w3[:]+w4[:])
          return (ft)
                        def projectParticlesToLattice(w1,w2,w3,w4,trIX,trIY,f,ft,tw):
                                 f[:,:]=0.0
   Compact.
                                 tw[:,:]=0.0
   Easy to
                                 f[trIX[:],trIY[:]]+=ft[:]*w1[:]
                                 f[trIX[:]+1,trIY[:]]+=ft[:]*w2[:]
    understand
                                                                               Node 1
                                 f[trIX[:],trIY[:]+1]+=ft[:]*w3[:]
                                                                            W.=1/L.
   and modify.
                                 f[trIX[:]+1,trIY[:]+1]+=ft[:]*w4[:]
                                                                            W_=1/L_
                                 tw[trIX[:],trIY[:]]+=w1[:]
   Minimum
                                                                            W,=1/L,
                                                                                   × Particle
                                 tw[trIX[:]+1,trIY[:]]+=w2[:]
                                                                            W_=1/L_
                                 tw[trIX[:],trIY[:]+1]+=w3[:]
   memory
                                 tw[trIX[:]+1,trIY[:]+1]+=w4[:]
                                                                               Node 3
                                                                                            Node 4
   requirements
                                                                           F_{\text{Particle}} = (F_{N1}^* W_1 + F_{N2}^* W_2 + F_{N3}^* W_3 + F_{N4}^* W_4) / (W_1 + W_2 + W_3 + W_4)
                                 f[:,:]/=tw[:,:]
                                 return (f)
```

The computing challenge: particle in cell

 Applications to Mantle flow (nonlinear Stokes), Porous media flow (Darcy equation) and suspension dynamics.





Suspended particles

G. Morra, from Springer Book, soon in press.

Gunawardana and Morra, submitted to Journal of Geodynamics

Vectorized Upwind scheme vs pure particles method













The computing challenge.

How is Numerical Python so fast?

1. Vectorization of most operations. NO LOOPS.

In [27]: %timeit c=addArray(a,b) #standard python 1 loops, best of 3: 639 ms per loop In [28]: %timeit c=a+b #NumPy arrays broadcasting 100 loops, best of 3: 3.74 ms per loop

- 2. Cython (=C in Python) implementation of difficult routines.
- 3. Lower understanding of the machine operations.
- 4. Many extension libraries (mpi4py, pyCuda, petsc4py).

Considerations on 3D modeling

N=L/RES	Number Of	Solution	Earth
	Elements	Approach	$L = 10^4 km$
			RES:10km
Finite	Volume	Sparse Matrix	$N = 10^3$
Element	Cells	Multigrid	CPU time
	$O(N^3)$	Inversion time	$O(10^9)$
		$O(N^3)$	
Boundary	Surface	Dense Matrix	$N = 10^3$
Element	Panels	Inversion time	CPU time
	$O(N^2)$	$O(N^2 * N^2)$	$O(10^{12})$



Immediate 3d modeling with NumPy



1. Tree representation

2. Fast Integration



3. Lagrangian motion

4. Cartesian representation



Immediate 3d modeling with NumPy

1. Tree representation:

from scipy import spatial
x, y, z = np.mgrid[0:5, 2:8, 3:7]
tree = spatial.KDTree(zip(x.ravel(), y.ravel(), z.ravel()))

- 2. Many-body calculations enable N-logN scaling.
- 3. Fast Integrals with NumPy
- 4. MPI Parallelization



def integralOverTriangle(collocationPosition, element,

- → gaussPoints, gaussWeights, xiCoord, etaCoord,
- → coords, nodesOnElement, alpha, beta, gamma):

Integrates the Green's function over a non-singular triangle # GE[0:3,0:3] are the integrated component # gaussPoints is the order of triangle quadrature

GE=np.zeros((3,3),float)

(gaussPosition, gaussNormalVector, gaussSurfaceMetrics, gaussDerivatives)=interpolate(coords[node1],coords[node2],coords[node3], coords[node4],coords[node5],coords[node6], alpha,beta,gamma, gaussXi,gaussEta, 1)

d = gaussPosition-collocationPosition dd = np.outer(d,d) i = np.identity(3) r = np.linalg.norm(d) velocityGreenFunction = i / r + dd / r**3

prefactor=0.5*gaussSurfaceMetrics*gaussWeights[gaussPoint]
GE += prefactor*velocityGreenFunction

return GE

Applications in global geodynamics and multiphase flow Morra et al., PEPI, 2010





Compaction (100%

Morra et al., 2015

Fast computing allows large scale models

Crustal Dynamics



Every bubble made by 1000 triangles!

Homogeneous Long wave Instability

Learning Fast Computing

A new generation of programming languages is emerging and replacing C, C++ and Fortran. Python is the most used, but other options have emerged emerge such as Julia and Ruby, or Java based Scala and Hadoop. Presently Python is the easiest, most compact and powerful and is replacing the glorious but not free and not open Matlab.



Revised and Expanded Editor John V. Guttag Some universities offer a mandatory "Introduction to Computer Science and Programming" at the beginning of every science program. Future geoscientists will use computing for every task. The earlier they familiarize with how computers "think", the sharper they will use their computing tools.

Many tools for machine learning are now mainly interfaced with Python. For example TensorFlow, from Google, that is open source and free to use, and allows organizing visual data/model output.



Conclusions and Perspectives

- Students and professionals have now more accessible tools to learn programming, which are simple and accessible new languages.
- Also hybrid approaches such as PARTICLES IN CELL and FAST MULTIPOLE -- BOUNDARY ELEMENTS can be implemented without great overhead because can be completely vectorized.
- For example by using Python geodynamics codes, in 2D as well as in 3D, are compact, run fast, are parallelized in a straightforward way.
- Most open projects are now interfaced, and sometimes directly developed, in Python and similar.
- To use Numerical Python and associated libraries is presently the EASY WAY TO learn COMPUTATIONAL GEODYNAMICS.

New initiatives

Gabriele Morra

Introduction to Python Geodynamics

Implementations for Fast Computing

September 24, 2016

Springer

An introductory level book on Geodynamics with Python, specifically for undergraduate students. Lecture Notes in Earth Sciences Springer Verlag.



Subduction Dynamics

From Mantle Flow to Mega Disasters



Gabriele Morra, David A. Yuen, Scott D. King, Sang Mook Lee and Seth Stein *Editors*

WILEY

@AGU

Special Volume with numerical techniques on geodynamics.

Big Data Training and International Conference on Haikou, Hainan Island, South China Sea. January 4 to 11, 2017 <u>http://mcdata-consult.com</u>